

# Visualizing PML

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# The PML Visualization Project

[dumas.io/PML](https://dumas.io/PML)

Joint work with **François Guéritaud**  
(Univ. Lille)

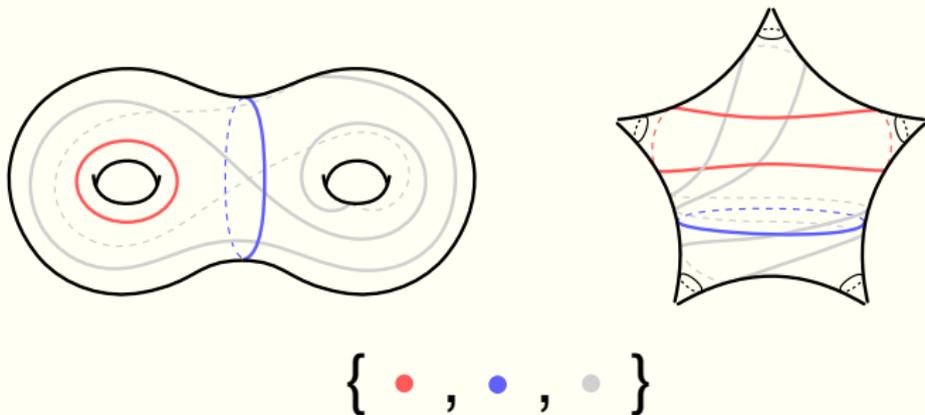
I will also demonstrate 3D graphics software developed by UIC undergraduate researchers **Galen Ballew** and **Alexander Gilbert**.



# What is PML?

The space of **P**rojective **M**easured **L**aminations

- A completion of the set  $\mathcal{C}$  of simple closed curves on  $S$
- Homeomorphic to  $\mathbf{S}^{N-1}$ , where  $N = \dim(\mathcal{T})$
- Piecewise linear structure, PL action of  $\text{Mod}(S)$



# Linear analogy

The inclusions

$$\mathcal{C} \hookrightarrow \text{ML} \quad (\text{discrete image})$$

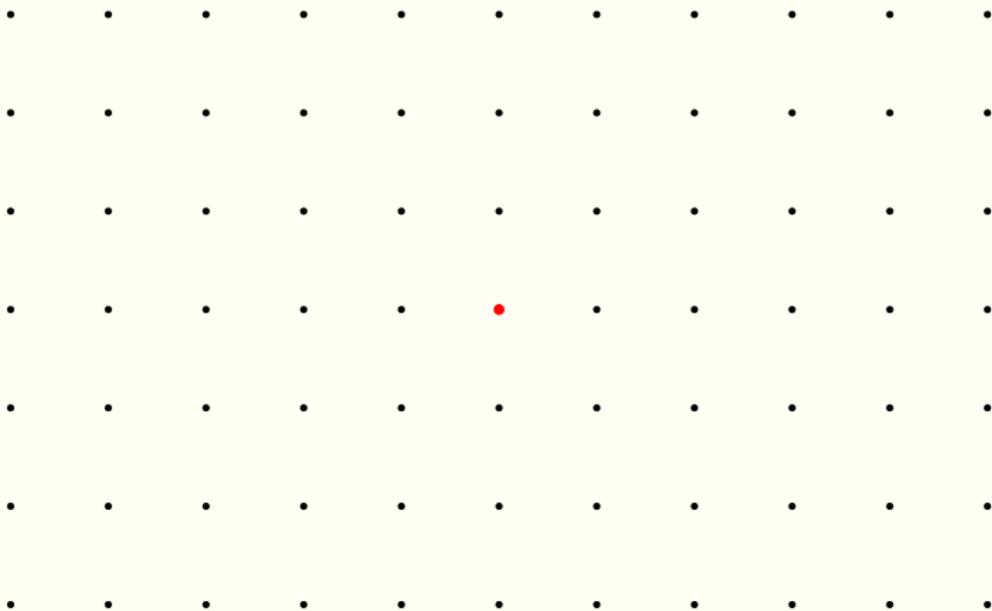
$$\mathcal{C} \hookrightarrow \text{PML} \quad (\text{dense image})$$

are analogous to

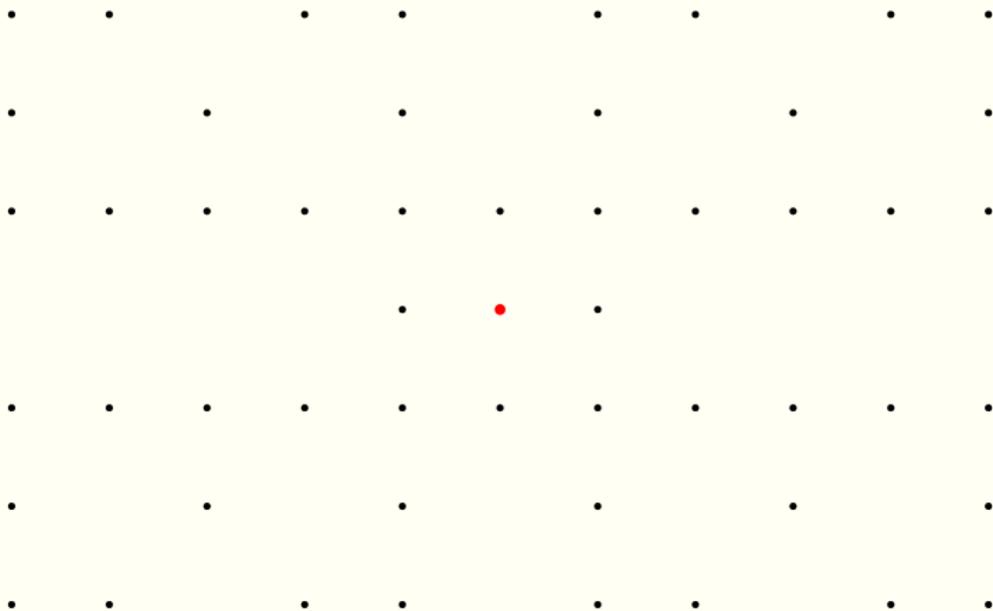
$$\text{primitive}(\mathbf{z}^N) \hookrightarrow \mathbf{R}^N \quad (\text{discrete image})$$

$$\text{primitive}(\mathbf{z}^N) \hookrightarrow \mathbf{S}^{N-1} \quad (\text{dense image})$$

# Linear visualization

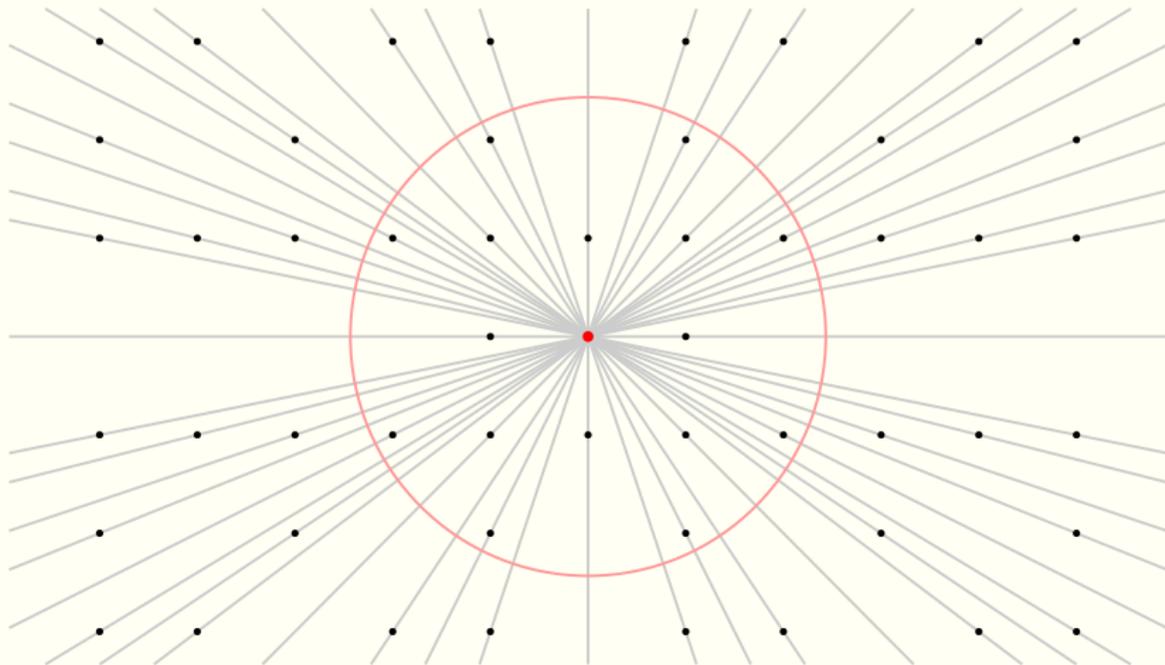


# Linear visualization

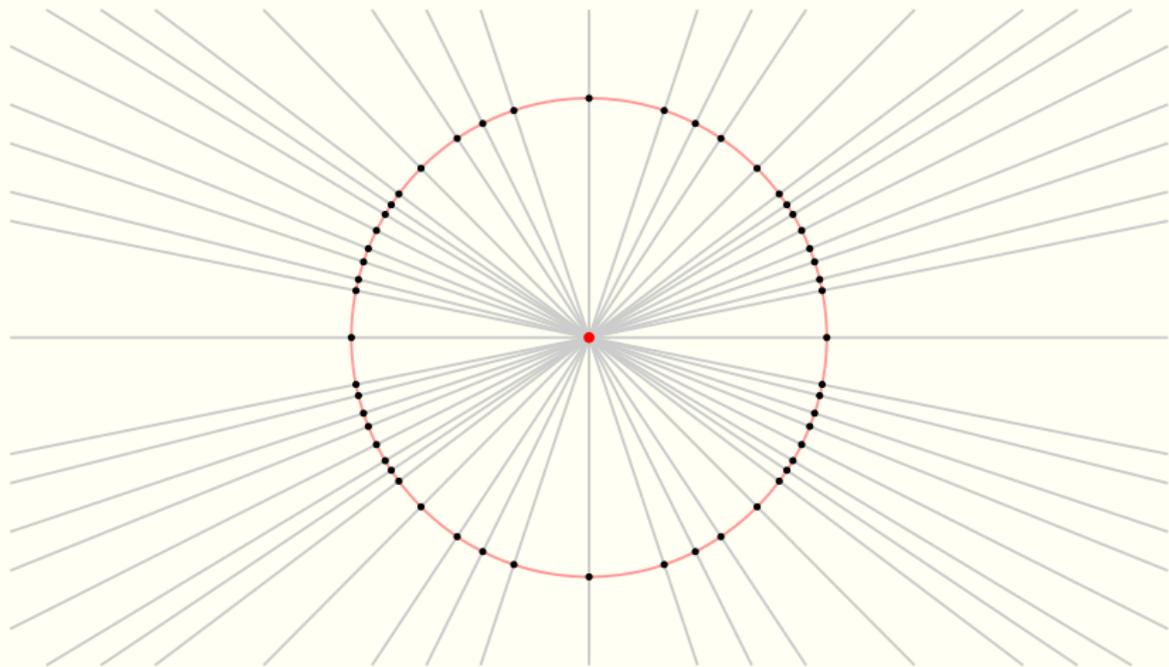




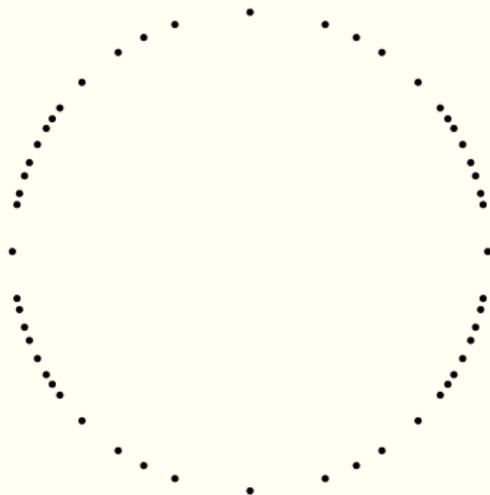
# Linear visualization



# Linear visualization



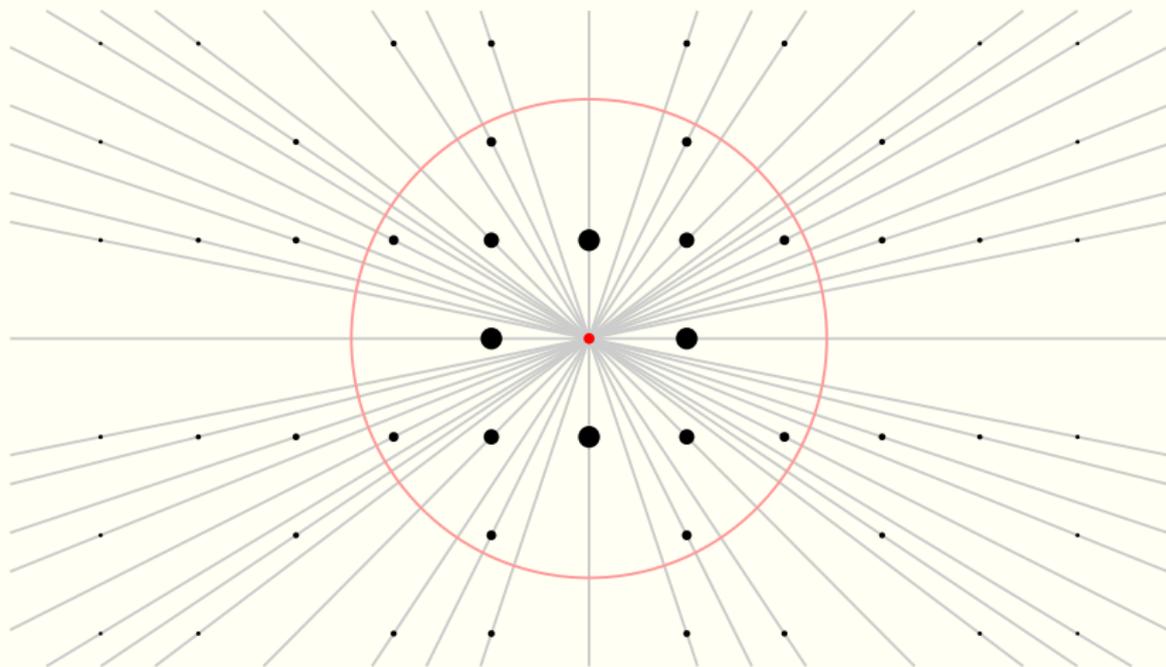
# Linear visualization



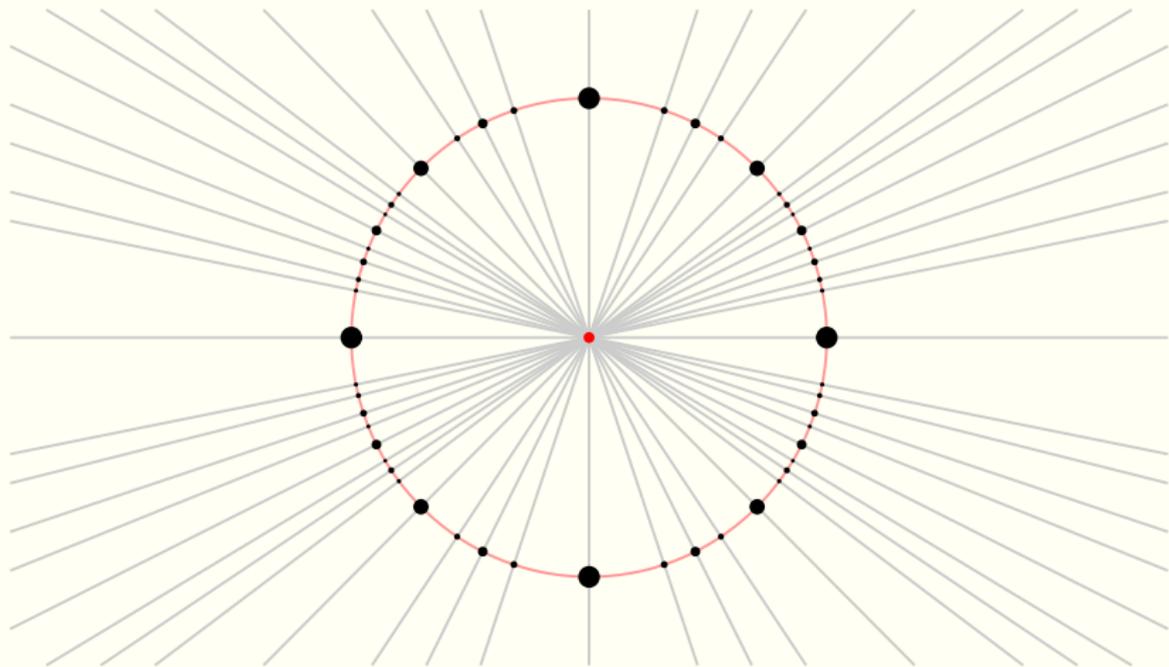




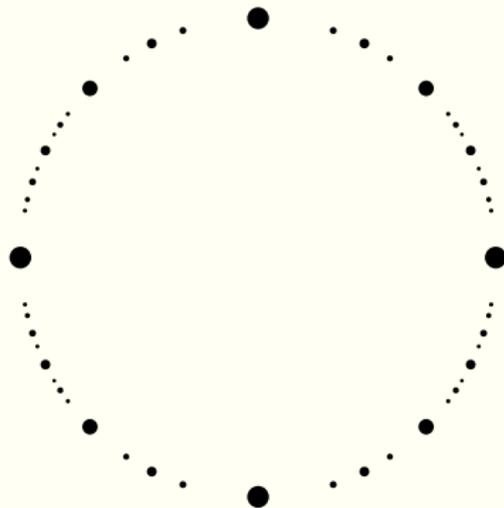
# Linear visualization



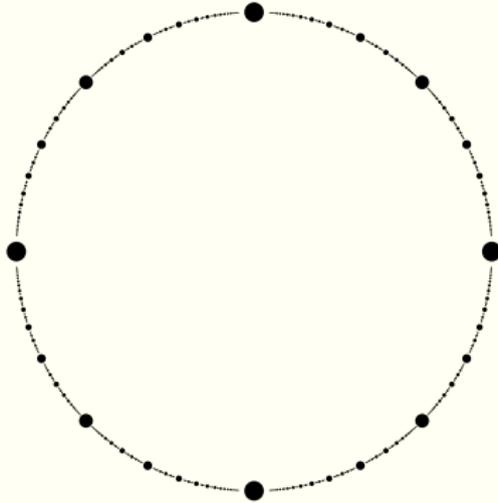
# Linear visualization



# Linear visualization



# Linear visualization



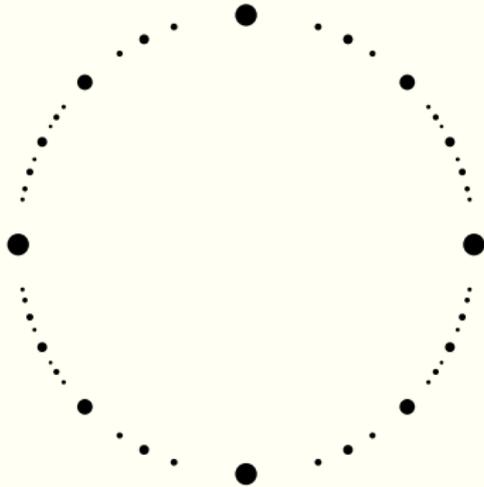
# Not so fast

Can we visualize PML similarly?

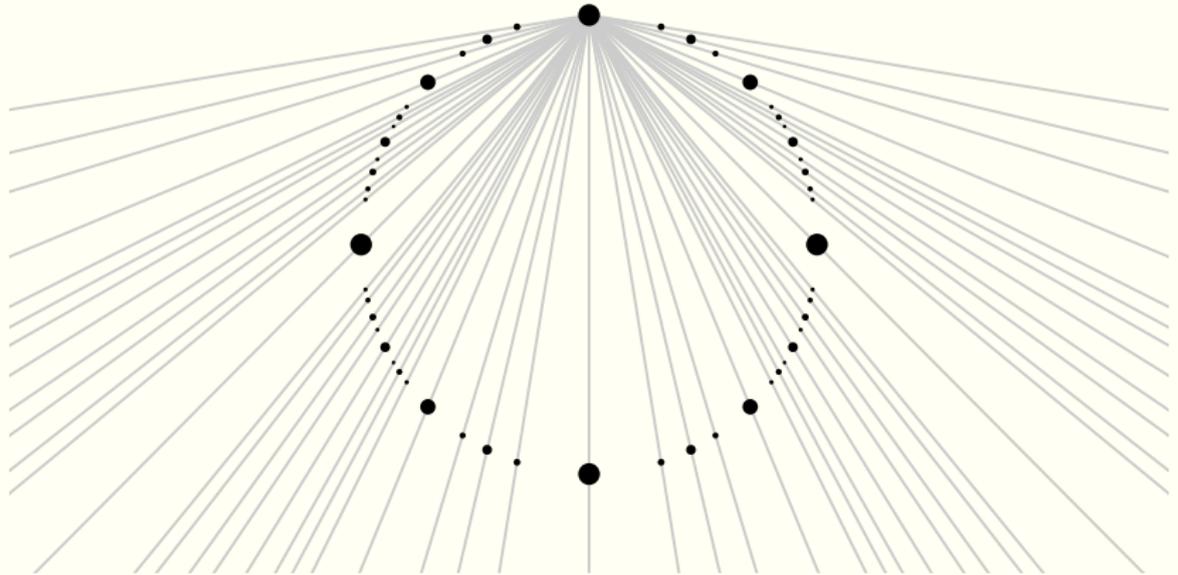
Several issues:

- Need to choose an identification  $ML \simeq \mathbf{R}^N$ .  
(Train tracks? Dehn-Thurston? Something else?)
- The “small” values of  $N = 6g - 6 + 2n$  are
  - N=2 for  $S_{0,4}$  and  $S_{1,1}$
  - N=4 for  $S_{0,5}$  and  $S_{1,2}$

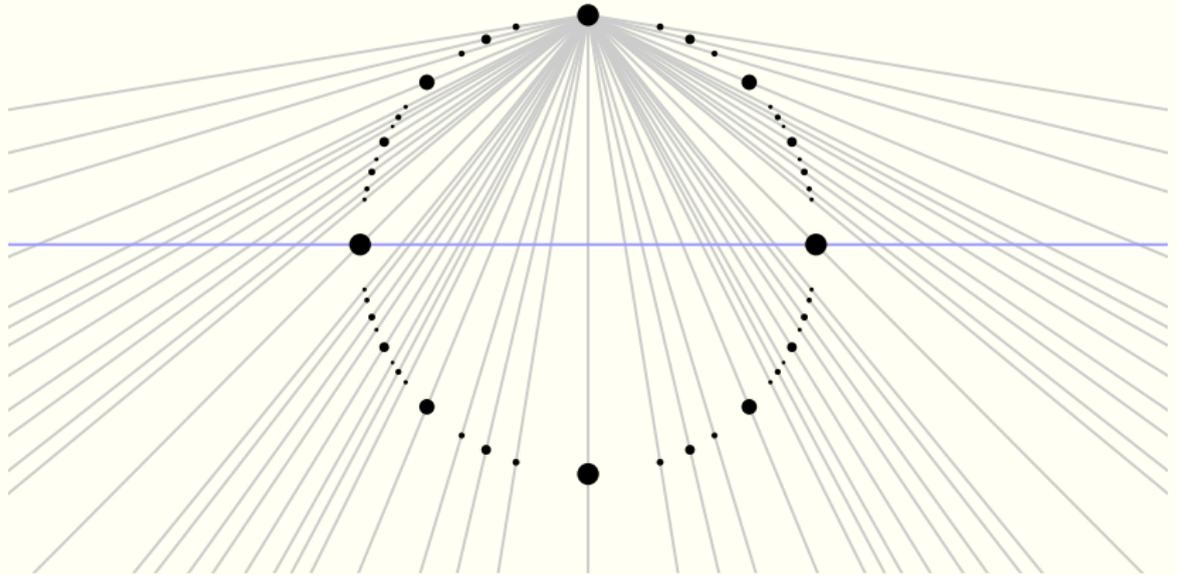
# Stereographic projection



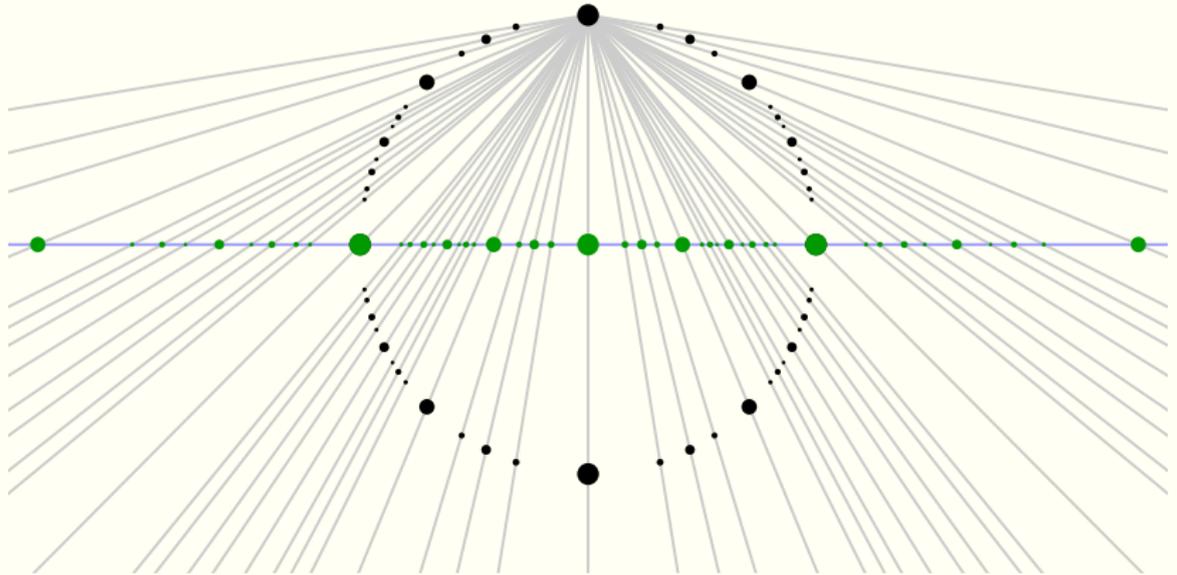
# Stereographic projection



# Stereographic projection



# Stereographic projection



# Stereographic projection



# Stereographic projection



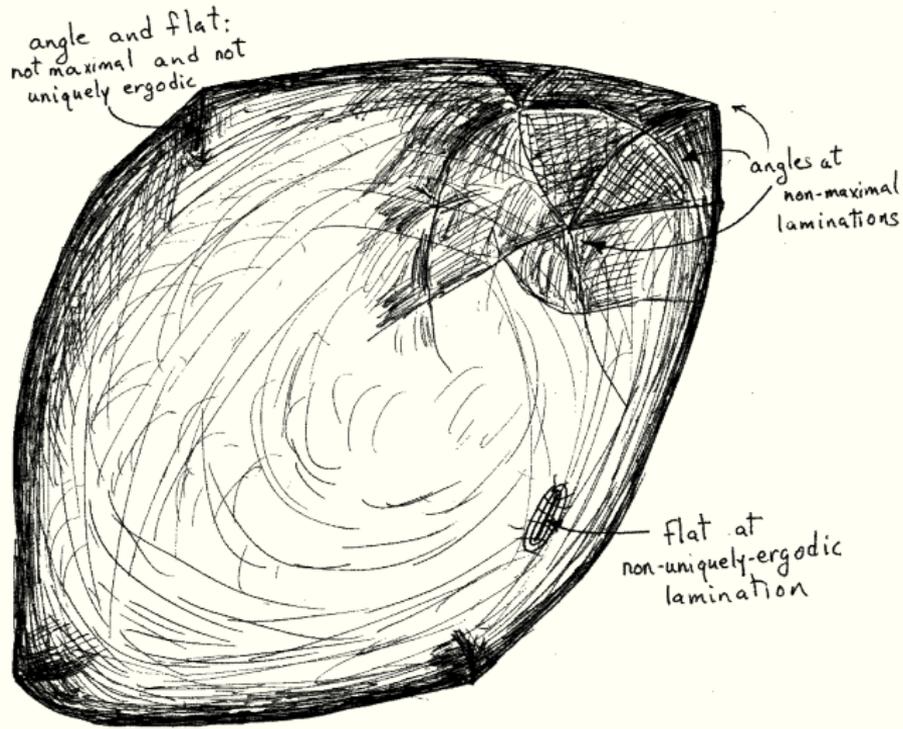
# Thurston's embedding

Fix  $X \in \mathcal{T}(S)$ , the **base hyperbolic structure**.

$$\begin{aligned} \text{PML} &\rightarrow T_X^* \mathcal{T}(S) \\ [\lambda] &\mapsto d_X \log(\ell_\lambda) \end{aligned}$$

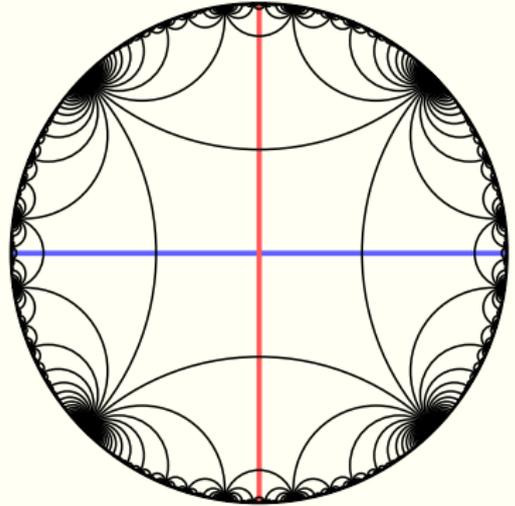
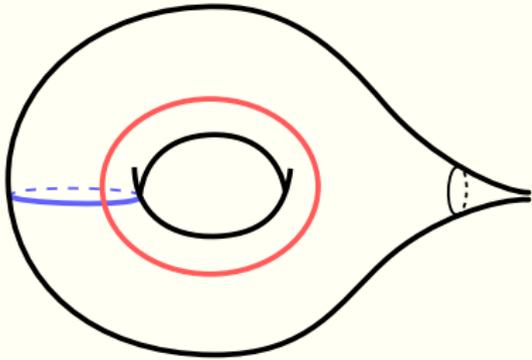
Curve  $\alpha \in \mathcal{C}$  maps to a vector representing the **sensitivity** of its geodesic length to deformations of the hyperbolic structure  $X$ .

# Thurston's drawing of PML



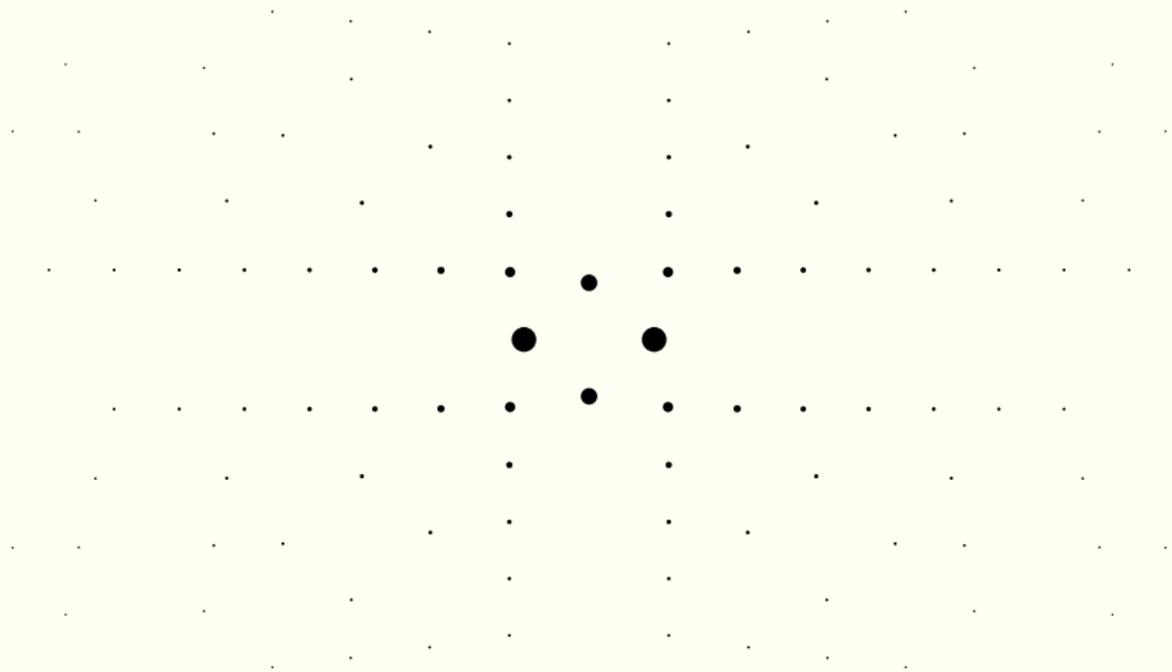
From "Minimal stretch maps between hyperbolic surfaces", preprint, 1986.

# Punctured torus

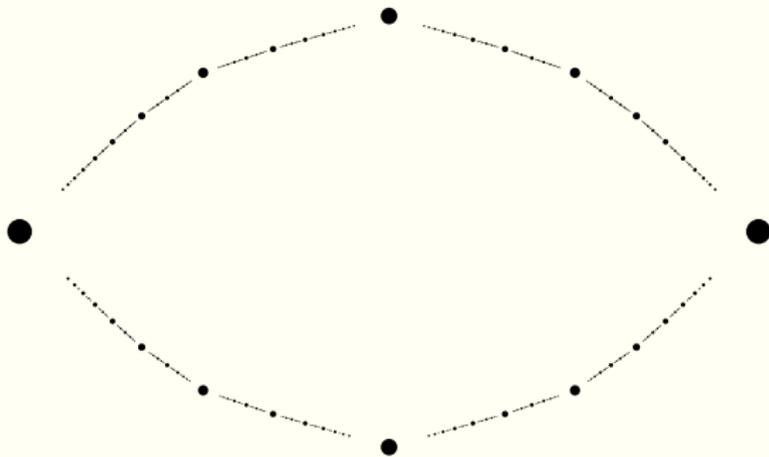


$S_{1,1}$

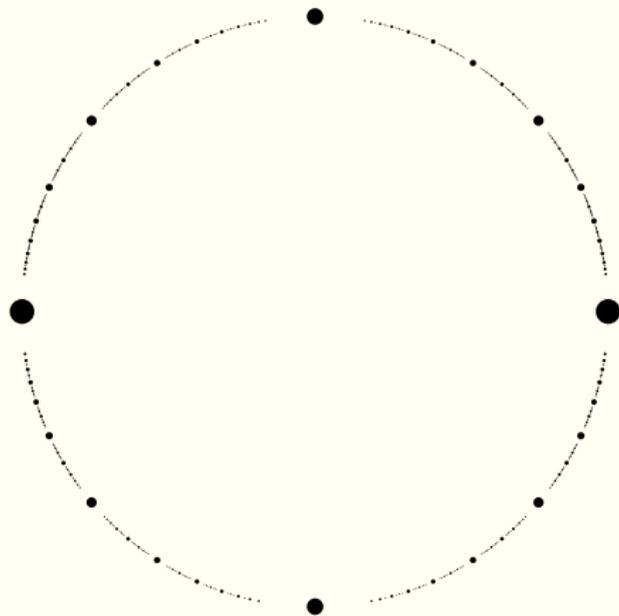
# Punctured torus



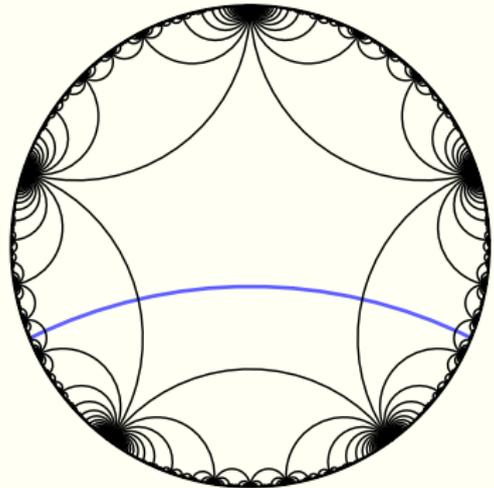
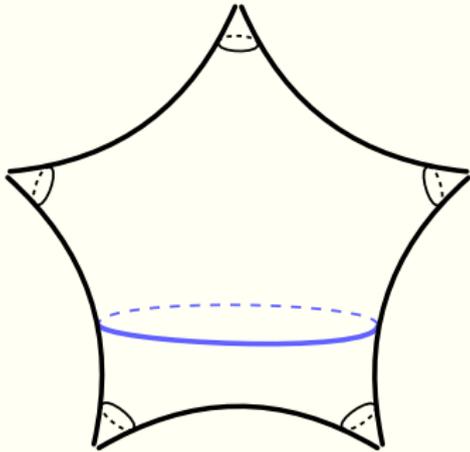
# Punctured torus



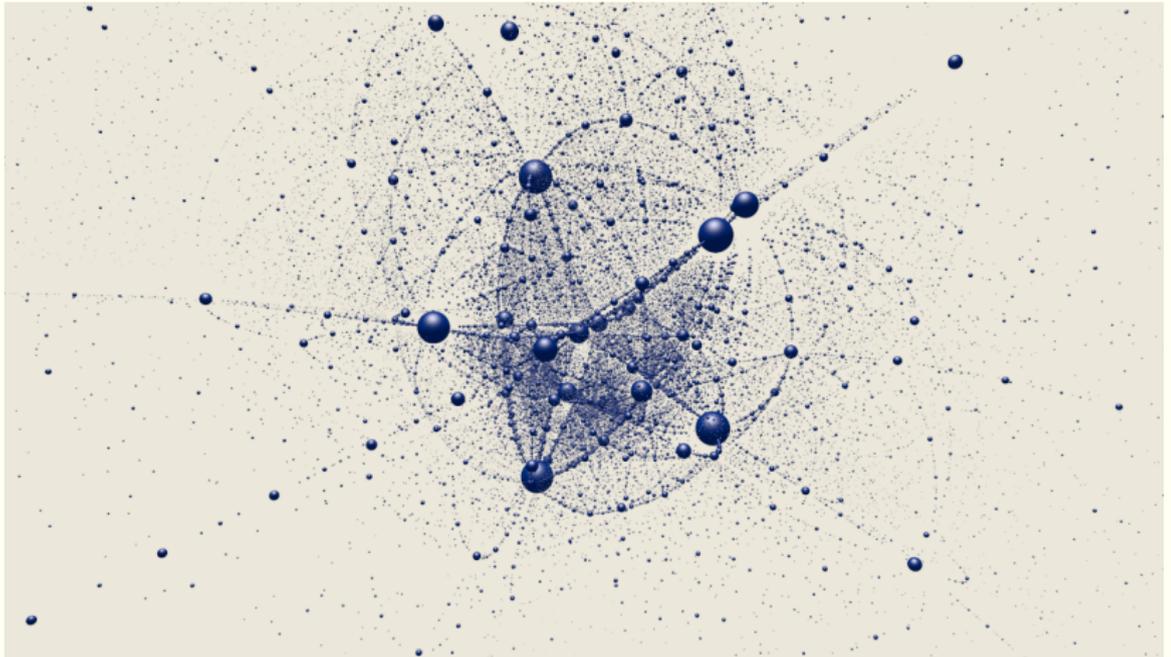
# Punctured torus



# Five-punctured sphere

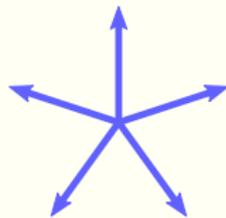
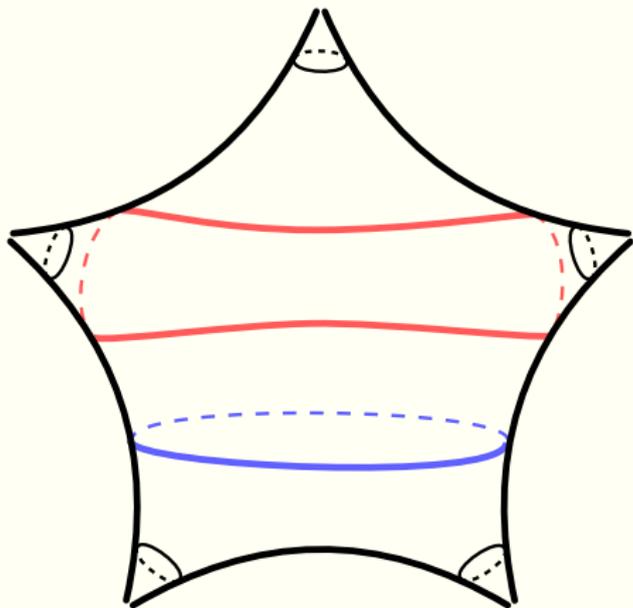


$S_{0,5}$



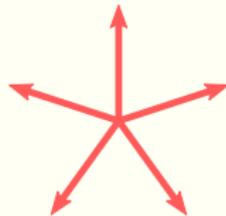
pmls05-001

# Earthquake basis



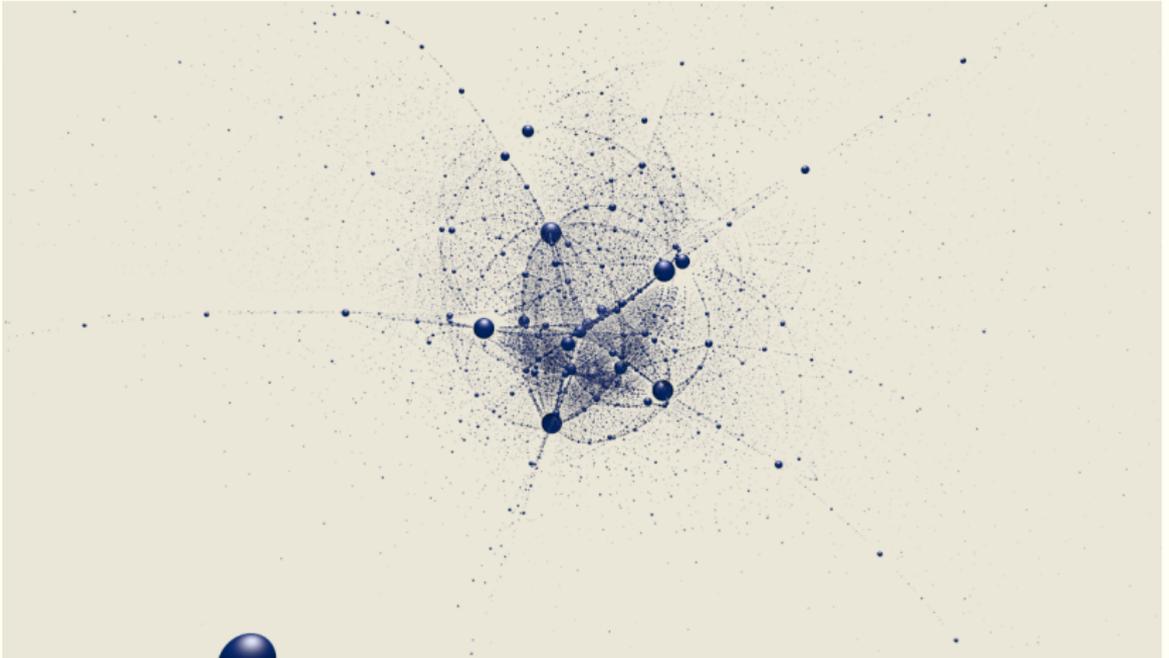
$\mathbf{R}^2$

$\oplus$



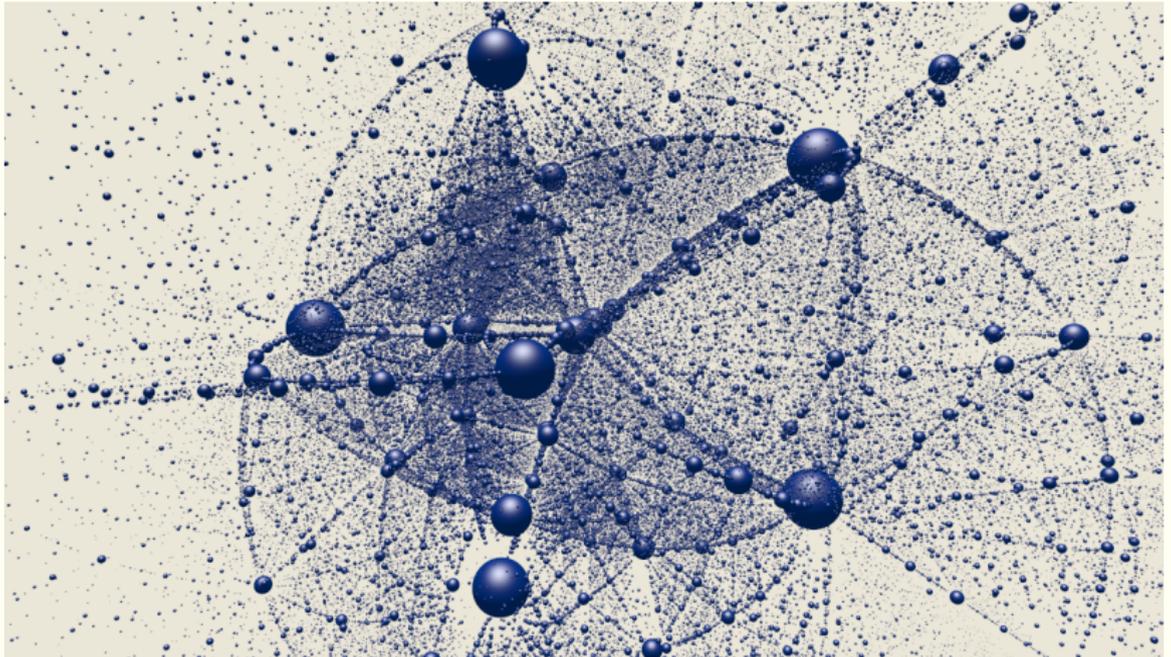
$\mathbf{R}^2$

## Rotating the pole



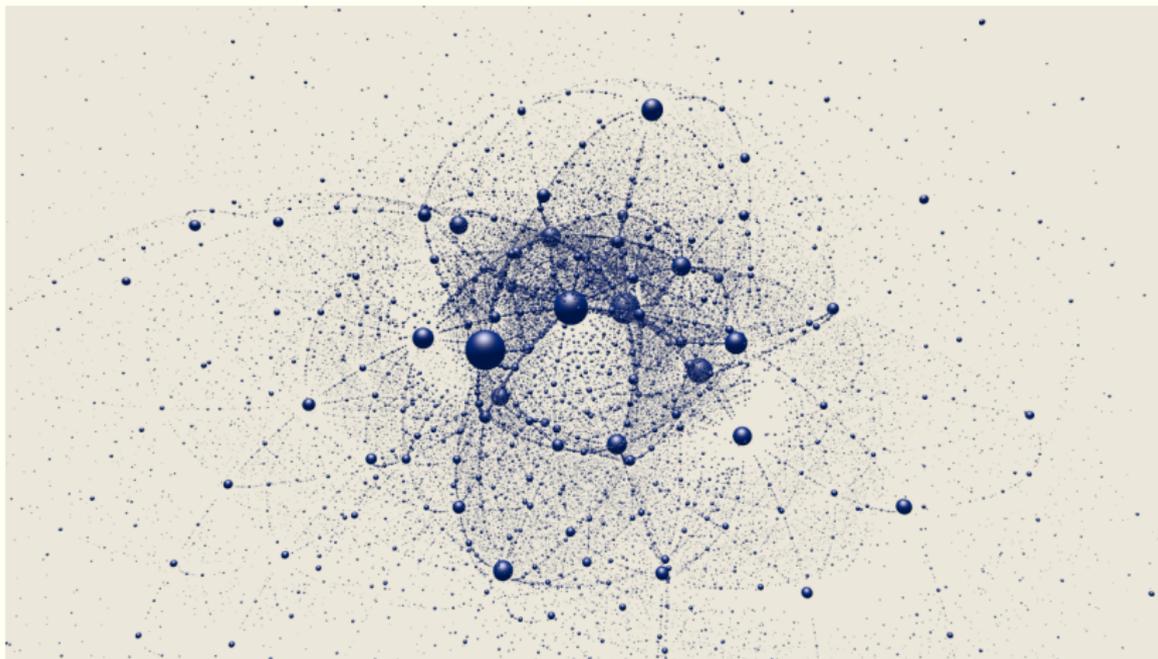
pmls05-010

Closer?



pmls05-020

# Clifford flow



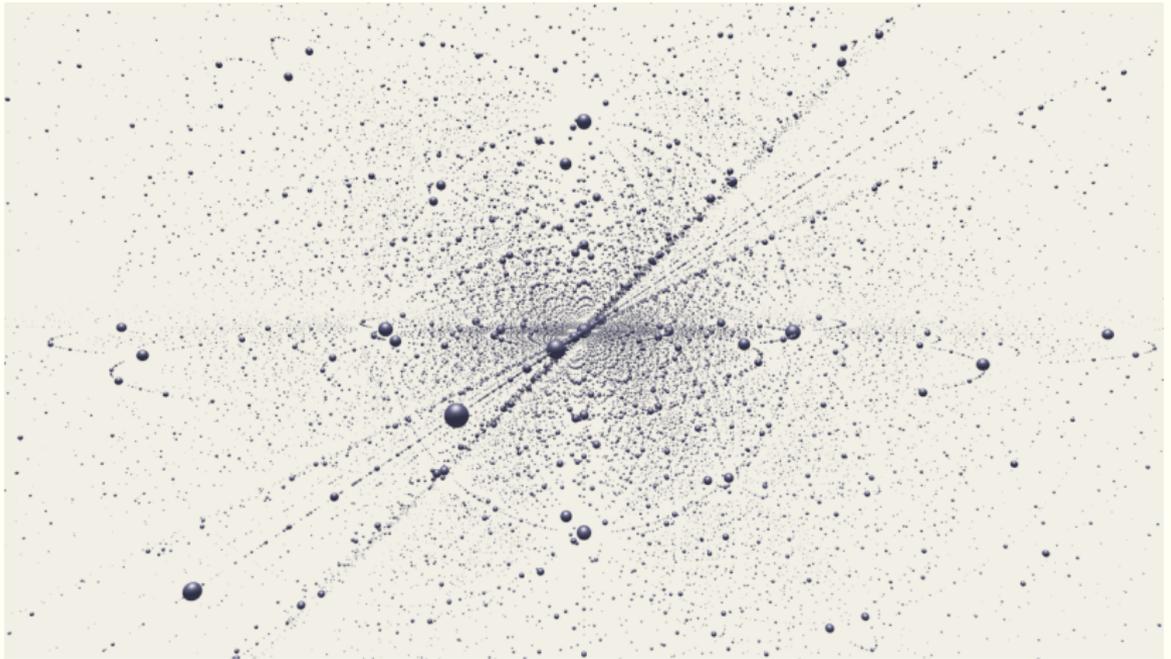
pmls05-030

# Back to the linear analogy

It is “easy” to imagine  $\mathbf{z}^4$ .

What about its stereographic projection?

And can this inform our understanding of the  $\text{PML}(S_{0,5})$  images?

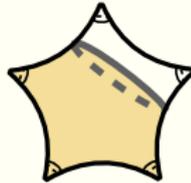
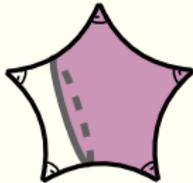
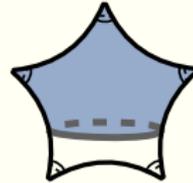
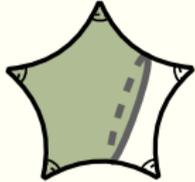


z4-011

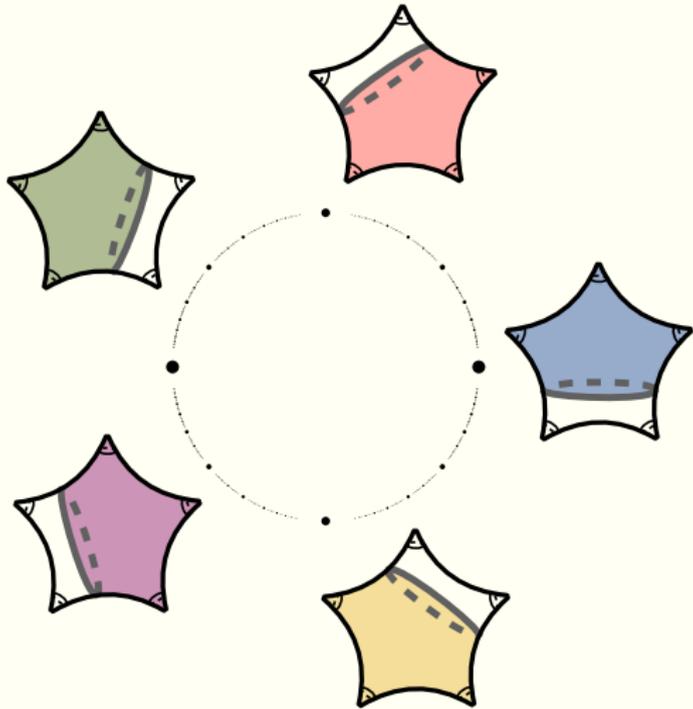
# Rings

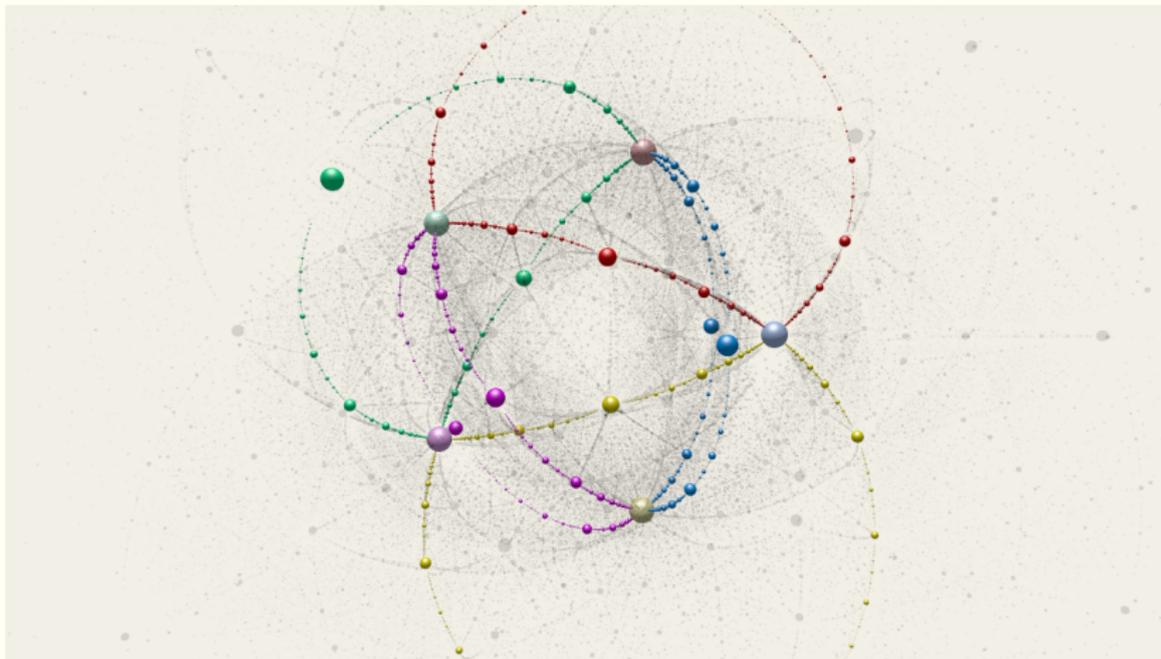


# Rings



# Rings





pmls05-071

# Contact

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