Homework 6

Due Monday, October 3, 2022 at 11:59pm

The same instructions given on homework 1 and 2 apply.

- (P1) For any $n \ge 1$, construct a smooth vector field on \mathbb{S}^n that vanishes at exactly one point. Hint: Use the stereographic projection charts.
- (P2) Let $SL_2 \mathbb{R}$ denote the set of 2×2 matrices of determinant 1, which is a smooth manifold of dimension 3. (For example, it is the preimage det⁻¹(1), and 1 is a regular value of det : $Mat_{2\times 2}\mathbb{R} \to \mathbb{R}$.) Recall that the product of two matrices of determinant 1 also has determinant 1, which will be helpful in this problem.
 - (a) Let *I* denote the 2 × 2 identity matrix. Here are three smooth paths $\mathbb{R} \to SL_2 \mathbb{R}$ that go through *I* at t = 0:

•
$$\gamma_1(t) = \begin{pmatrix} e^t & 0\\ 0 & e^{-t} \end{pmatrix}$$

• $\gamma_2(t) = \begin{pmatrix} 1 & t\\ 0 & 1 \end{pmatrix}$

•
$$\gamma_3(t) = \begin{pmatrix} 1 & 0 \\ t & 1 \end{pmatrix}$$

Show that their velocity vectors, $\{\gamma'_i(0) \mid 1 \le i \le 3\}$, form a basis of $T_I \operatorname{SL}_2 \mathbb{R}$.

- (b) Let $m = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL_2 \mathbb{R}$. Construct an explicit basis of $T_m SL_2 \mathbb{R}$. Suggestion: Use part (a) and the matrix multiplication operation on $SL_2 \mathbb{R}$.
- (P3) As in the previous problem, $SL_2\mathbb{R}$ denotes the 3-dimensional manifold consisting of all 2×2 matrices of determinant 1.
 - (a) Let tr : $SL_2 \mathbb{R} \to \mathbb{R}$ denote the trace map, which takes a matrix to the sum of its diagonal entries, i.e.

$$\operatorname{tr}\begin{pmatrix}a&b\\c&d\end{pmatrix} = a+d$$

(But note we've restricted attention to matrices of determinant 1.)

What are the regular values of this function?

(b) Suppose $\lambda > 1$. Show that the set of matrices

 $\{A \in \operatorname{SL}_2 \mathbb{R} \mid \lambda \text{ is an eigenvalue of } A\}$

is an embedded submanifold of $SL_2 \mathbb{R}$. What is its dimension?